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The KUKA control panel is the interface to the robot controller and to the robot. This document gives an schematic overview of the buttons and symbols. Do note however that this document does not replace the KUKA documentation. This document is valid for most KR C1 and all KR C2 robot controllers.

The series 2000 shelf-mounted robots comprise the KR 150-2 K, KR 180-2 K and KR 210-2 K. KUKA shelf-mounted robots are ideal for unloading parts from injection molding machines. The low base is specially optimized for working downwards. Drive system, electromechanical with brushless AC servomotors \*to ISO 9283

I enrolled in Programming 1. The course spans a full 40-hour week, mixing classroom learning and lab practice, with students programming KUKA KR3 Agilus robots set up in special education cells. The course covers the KRC4 controller, but courses in the older KRC2 programming are also available.

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RoboDK supports all KUKA robot controllers since KRC2, including KUKA KRC3 and KRC4 controllers. This documentation is based on a KRC4 controller. The KRC4 robot controller runs the Microsoft Embedded Windows 7 operating system. Previous controllers, such as KRC2, run Windows 95. The robot teach pendant shows an "HMI" which is a program that KUKA developed to run on Windows and it is the ...

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