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The OpenNI library provides a general framework for working with various depth cameras using the following classes: OpenNI is used for initialization of work with the library. It provides information about errors, version of the library, devices found. Device is a connected device.

Acquisition - `openni_nite_acquisition`. This is a helper application used to collect RGB, depth images, as well as landmark positions from a sensor connected to the computer. It needs OpenNI and NiTE2 to work, not bundled here due to licensing issues. tracking

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~~GitHub — OpenNI/OpenNI: OpenNI~~

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